

**Lecture 34.** November 16, 2016

**Topics:** Horizontal momentum equations in the isobaric coordinates. Total derivative in the isobaric coordinates. Continuity and thermodynamic energy equations in the isobaric coordinates.

**Reading:** Holton and Hakim Section 3.1.

### 1. Horizontal momentum equations

The horizontal momentum equations are approximate equations of horizontal motion that may be obtained by scale analysis from the general-form momentum equation,

$$\frac{d\mathbf{U}}{dt} = -\frac{1}{\rho} \nabla p + \mathbf{g} - 2\boldsymbol{\Omega} \times \mathbf{U} + \mathbf{F}_r.$$

by retaining only main (that is, representative of the synoptic-scale motions) terms in the individual equations for  $x$  and  $y$  components of momentum balance (see Class 29). These horizontal momentum equations appear as

$$\begin{aligned} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} &= -\frac{1}{\rho} \frac{\partial p}{\partial x} + fv, \\ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} &= -\frac{1}{\rho} \frac{\partial p}{\partial y} - fu. \end{aligned}$$

where  $f = 2\Omega \sin \varphi$  is the Coriolis parameter, and  $u$  and  $v$  are, respectively,  $x$  and  $y$  components of the horizontal wind velocity vector  $\mathbf{V} = \mathbf{i}u + \mathbf{j}v$ .

In vector form, we can write these two equations as a single vector equation,

$$\frac{d\mathbf{V}}{dt} + f\mathbf{k} \times \mathbf{V} = -\frac{1}{\rho} \nabla p,$$

where  $\nabla = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y}$  is the horizontal del operator (in this case, we consider changes of the pressure field only in the horizontal  $X$ - $Y$  plane). **Note** that in this case we assume that horizontal derivatives are taken with  $z$  held constant.

### 2. Expression of pressure gradient in isobaric coordinates

Pressure as a vertical coordinate was considered in Class 25, where the following relationships between the components of pressure gradient force in  $x, y, z$  and  $x, y, p$  coordinate systems were obtained:

$$\left(\frac{\partial p}{\partial x}\right)_z = -\left(\frac{\partial p}{\partial z}\right)_x \left(\frac{\partial z}{\partial x}\right)_p \quad \text{and} \quad \left(\frac{\partial p}{\partial y}\right)_z = -\left(\frac{\partial p}{\partial z}\right)_y \left(\frac{\partial z}{\partial y}\right)_p.$$

Using the hydrostatic approximation and the approximate form of the geopotential  $\Phi$  change with height,

$$\frac{\partial p}{\partial z} = -\rho g \quad \text{and} \quad \frac{\partial \Phi}{\partial z} = g,$$

we come to

$$(1/\rho)(\partial p/\partial x)_z = (\partial\Phi/\partial x)_p \text{ and } (1/\rho)(\partial p/\partial y)_z = (\partial\Phi/\partial y)_p,$$

so we can write down the horizontal momentum equation (p. 1) in vector form as

$$\frac{d\mathbf{V}}{dt} + f\mathbf{k} \times \mathbf{V} = -\nabla_p \Phi,$$

where  $\nabla_p = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y}$  is the horizontal gradient operator applied along isobaric surfaces (that is, with pressure  $p$  held constant), and  $\mathbf{V} = \mathbf{i}u + \mathbf{j}v$  is horizontal velocity vector in isobaric (pressure) coordinates, where  $u$  and  $v$  are, respectively, components of velocity aligned with  $x$  and  $y$  directions in the isobaric coordinates.

Recalling that geostrophic balance in the equations of horizontal motion is introduced as a state of the flow, in which Coriolis and pressure-gradient forces balance each other (Class 29), we obtain the following isobaric-coordinate form of the geostrophic relationship:

$$f\mathbf{k} \times \mathbf{V}_g = -\nabla_p \Phi,$$

or

$$\mathbf{V}_g = \frac{1}{f}(\mathbf{k} \times \nabla_p \Phi),$$

where  $\mathbf{V}_g = \mathbf{i}u_g + \mathbf{j}v_g$  is the geostrophic wind in the isobaric coordinates. This relationship means that, as long as Coriolis parameter  $f$  may be considered constant, geostrophic wind field on the isobaric surface is locally non-divergent:

$$\nabla_p \cdot \mathbf{V}_g = \frac{1}{f} \nabla_p \cdot (\mathbf{k} \times \nabla_p \Phi) = 0,$$

(please be able to demonstrate it yourself).

### 3. Total (substantial) derivative in isobaric coordinates

In the isobaric coordinates, the *total* (also called *substantial* or *material*) derivative with respect to time,  $\frac{d}{dt}$ , acquires the form:

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \frac{dx}{dt} \frac{\partial}{\partial x} + \frac{dy}{dt} \frac{\partial}{\partial y} + \frac{dp}{dt} \frac{\partial}{\partial p}.$$

The above formula is obtained based on the same considerations as the expression of the total derivative in the Cartesian coordinates:

$$\frac{d}{dt} = \frac{\partial}{\partial t} + \frac{dx}{dt} \frac{\partial}{\partial x} + \frac{dy}{dt} \frac{\partial}{\partial y} + \frac{dz}{dt} \frac{\partial}{\partial z}.$$

Denoting  $\frac{dp}{dt} \equiv \omega$ , and using the conventional notation for the horizontal velocity components,  $u \equiv \frac{dx}{dt}$  and  $v \equiv \frac{dy}{dt}$ , we come to

$$\frac{d}{dt} = \frac{\partial}{\partial t} + u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + \omega \frac{\partial}{\partial p}.$$

**Note** that  $\omega \equiv \frac{dp}{dt}$  is the isobaric-system counterpart of the Cartesian vertical velocity  $w \equiv \frac{dz}{dt}$ , so the complete velocity vector in the isobaric coordinates is given by  $\mathbf{U} = (\mathbf{V}, \omega)$ .

#### 4. Continuity equation in the isobaric coordinates

In the Cartesian coordinates, the continuity equation (that is an expression for the conservation of mass in a moving fluid) is written in the following forms previously considered throughout the course:

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} + \frac{\partial \rho w}{\partial z} = 0, \quad \frac{\partial \rho}{\partial t} + \nabla \cdot \rho \mathbf{U} = 0, \quad \frac{d\rho}{dt} + \rho \nabla \cdot \mathbf{U} = 0.$$

To derive the expression for conservation of mass in the isobaric coordinate system, where the coordinates are  $x$ ,  $y$ ,  $p$ , and  $t$ , we recall that  $p$  may be related to  $z$  through the hydrostatic balance equation:

$$\partial p / \partial z = -\rho g.$$

We may thus write down the mass conservation principle for a moving fluid parcel with mass

$$\delta M = \rho \delta V = \rho \delta x \delta y \delta z = -\delta x \delta y \frac{\delta p}{g} = -\frac{\delta x \delta y \delta p}{g}$$

as

$$\frac{1}{\delta M} \frac{d}{dt} \delta M = \frac{g}{\delta x \delta y \delta p} \frac{d}{dt} \frac{\delta x \delta y \delta p}{g} = \frac{1}{\delta x \delta y \delta p} \frac{d}{dt} \delta x \delta y \delta p = 0 \text{ (the mass } \delta M \text{ is conserved!).}$$

Performing differentiation in the third term of the above relationship:

$$\frac{1}{\delta x \delta y \delta p} \frac{d}{dt} \delta x \delta y \delta p = \frac{1}{\delta x} \frac{d}{dt} \delta x + \frac{1}{\delta y} \frac{d}{dt} \delta y + \frac{1}{\delta p} \frac{d}{dt} \delta p = \frac{1}{\delta x} \delta \left( \frac{dx}{dt} \right) + \frac{1}{\delta y} \delta \left( \frac{dy}{dt} \right) + \frac{1}{\delta p} \delta \left( \frac{dp}{dt} \right) = 0,$$

and recalling that the vertical velocity  $\omega$  in the isobaric  $(x, y, p, t)$  coordinate system is defined as  $\omega \equiv \frac{dp}{dt}$  (see

p. 3), we come to

$$\frac{\delta u}{\delta x} + \frac{\delta v}{\delta y} + \frac{\delta \omega}{\delta p} = 0,$$

which in the limit of  $\delta x, \delta y, \delta p \rightarrow 0$  provides the continuity equation in the isobaric coordinate system,

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial \omega}{\partial p} = 0.$$

**Note** that in the above equation, the partial derivatives in  $x$  and  $y$  directions are evaluated at constant pressure.

## 5. Heat balance (thermodynamic energy) equation in the isobaric coordinates

In the Cartesian coordinates, the heat balance (thermal energy) equation – that is an expression of the first law of thermodynamic in a moving fluid – reads (in one of its previously discussed forms, see Class 33):

$$c_p \frac{dT}{dt} - \alpha \frac{dp}{dt} = J ,$$

where the total derivative with respect to time is given by

$$\frac{d}{dt} = \frac{\partial}{\partial t} + u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} .$$

Substituting into the thermal energy equation the expressions of the total derivatives of temperature and pressure in the isobaric coordinates,

$$\frac{dT}{dt} = \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + \omega \frac{\partial T}{\partial p} \text{ and } \omega = \frac{dp}{dt} ,$$

and using the gas law that provides

$$\alpha = \frac{1}{\rho} = \frac{RT}{p} ,$$

we arrive at the following heat balance equation in the isobaric coordinates:

$$\left( \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) - \omega \left( \frac{RT}{c_p p} - \frac{\partial T}{\partial p} \right) = \frac{J}{c_p} .$$

From the definition of potential temperature  $\theta$  (Class 33),

$$\theta = T(p_0 / p)^{R/c_p} ,$$

it follows that

$$\frac{\partial \ln \theta}{\partial p} = \frac{\partial \ln T}{\partial p} - \frac{R}{c_p} \frac{\partial \ln p}{\partial p} ,$$

which may be rewritten as

$$\frac{T}{\theta} \frac{\partial \theta}{\partial p} = \frac{\partial T}{\partial p} - \frac{RT}{c_p p} \frac{\partial p}{\partial p} ,$$

or

$$\frac{RT}{c_p p} - \frac{\partial T}{\partial p} = -\frac{T}{\theta} \frac{\partial \theta}{\partial p} \equiv S_p ,$$

where  $S_p$  may be interpreted as the parameter of hydrostatic stability in the isobaric coordinate system. Because

$$\frac{T}{\theta} \frac{d\theta}{dz} = \frac{dT}{dz} + \frac{g}{c_p} = \Gamma_d - \Gamma ,$$

see Class 33, we may express stability parameter  $S_p$  as

$$S_p = -\frac{T}{\theta} \frac{\partial \theta}{\partial z} \frac{\partial z}{\partial p} = \frac{T}{\theta} \frac{\partial \theta}{\partial z} \frac{1}{\rho g} = \frac{\Gamma_d - \Gamma}{\rho g},$$

so  $S_p$  is positive when  $\Gamma < \Gamma_d$  (subadiabatic regime,  $\frac{\partial \theta}{\partial z} > 0$ ; the atmosphere is stable) and  $S_p$  is negative

when  $\Gamma > \Gamma_d$  (superadiabatic regime,  $\frac{\partial \theta}{\partial z} < 0$ ; the atmosphere is unstable) Under neutral conditions

( $\Gamma = \Gamma_d$ ;  $\frac{\partial \theta}{\partial z} = 0$ ), parameter  $S_p$  goes to zero.

The heat balance equation in the isobaric coordinates thus may be written in terms of  $S_p$  and  $\omega$  as

$$\left( \frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} \right) - S_p \omega = \frac{J}{c_p},$$

or

$$\frac{\partial T}{\partial t} + \mathbf{V} \cdot \nabla_p T - S_p \omega = \frac{J}{c_p},$$

where  $\nabla_p = \mathbf{i} \frac{\partial}{\partial x} + \mathbf{j} \frac{\partial}{\partial y}$  is applied along the isobaric surfaces, see p. 2.