

Lecture 12. September 19, 2016

Topics: Vector differentiation with respect to a scalar argument. Directional derivative and gradient of a scalar field. Del (nabla) operator. Definitions and properties of divergence and curl.

Reading: Appendix C of Holton and Hakim, and section 3.5 of Fiedler.

1. Vector differentiation

Derivative $\frac{d\mathbf{v}}{dt}$ of vector function \mathbf{v} (e.g., velocity) with respect to a scalar argument t (e.g., time) is defined as

$$\frac{d\mathbf{v}}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\mathbf{v}(t + \Delta t) - \mathbf{v}(t)}{\Delta t}.$$

Properties:

$$\frac{d(\mathbf{v} + \mathbf{w})}{dt} = \frac{d\mathbf{v}}{dt} + \frac{d\mathbf{w}}{dt},$$

$$\frac{dc\mathbf{v}}{dt} = c \frac{d\mathbf{v}}{dt} \quad (\text{where } c \text{ is a scalar constant}),$$

$$\frac{d(\mathbf{v} \cdot \mathbf{w})}{dt} = \mathbf{v} \cdot \frac{d\mathbf{w}}{dt} + \mathbf{w} \cdot \frac{d\mathbf{v}}{dt},$$

$$\frac{d(\mathbf{v} \times \mathbf{w})}{dt} = \mathbf{v} \times \frac{d\mathbf{w}}{dt} + \mathbf{w} \times \frac{d\mathbf{v}}{dt},$$

$$\frac{d|\mathbf{v}|}{dt} = \frac{1}{|\mathbf{v}|} \mathbf{v} \cdot \frac{d\mathbf{v}}{dt} \quad (\text{it is presumed that } \mathbf{v} \neq 0).$$

Examples of vector functions and vector-function derivatives:

Velocity (e.g., of a particle)

$$\mathbf{v} = \frac{d\mathbf{r}}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t)}{\Delta t} = \frac{dx}{dt} \hat{\mathbf{i}} + \frac{dy}{dt} \hat{\mathbf{j}},$$

where \mathbf{r} is the position vector.

In polar coordinates on a plane, as will be shown later,

$$\mathbf{v} = \frac{d\mathbf{r}}{dt} = \frac{dr\hat{\mathbf{r}}(\theta)}{dt} = \frac{dr}{dt} \hat{\mathbf{r}} + r \frac{d\hat{\mathbf{r}}(\theta)}{dt} = \frac{dr}{dt} \hat{\mathbf{r}} + r \frac{d\theta}{dt} \hat{\boldsymbol{\theta}}.$$

Acceleration,

$$\mathbf{a} = \frac{d\mathbf{v}}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\mathbf{v}(t + \Delta t) - \mathbf{v}(t)}{\Delta t} = \frac{d}{dt} \frac{d\mathbf{r}}{dt} = \frac{d^2\mathbf{r}}{dt^2}.$$

2. Directional derivative and gradient of a scalar field; del (nabla) operator

Consider a scalar function $T(x, y, z)$ of independent spatial variables x, y, z (we may consider it to be air temperature). Spatial derivative of T with respect to x , $\frac{\partial T}{\partial x}$, describes the rate of change of T in x direction (it would be an eastward change in temperature if the X axis is directed to the east). **Note** that while evaluating $\frac{\partial T}{\partial x}$, y and z values are kept constant. Analogously, $\frac{\partial T}{\partial y}$ and $\frac{\partial T}{\partial z}$ describe the rates of temperature change in y and z directions, respectively.

How could one evaluate the rate of change of temperature in an arbitrary direction?

Consider a spatial change specified by a vector $d\mathbf{m}$ that has coordinate components dx , dy , and dz :

$$d\mathbf{m} = dx\hat{\mathbf{i}} + dy\hat{\mathbf{j}} + dz\hat{\mathbf{k}}.$$

Like with other Cartesian vectors, one may introduce the magnitude of this vector, $dm = |d\mathbf{m}|$ and associated unit vector $\hat{\mathbf{m}} = \frac{d\mathbf{m}}{dm}$ (it is pointing in the same direction as $d\mathbf{m}$). In coordinate form, the unit vector $\hat{\mathbf{m}}$ is therefore presented as

$$\hat{\mathbf{m}} = \frac{dx}{dm}\hat{\mathbf{i}} + \frac{dy}{dm}\hat{\mathbf{j}} + \frac{dz}{dm}\hat{\mathbf{k}}.$$

Now consider the aggregated change of temperature $T(x, y, z)$ in x, y , and z directions associated with spatial displacements dx , dy , and dz :

$$dT = \frac{\partial T}{\partial x} dx + \frac{\partial T}{\partial y} dy + \frac{\partial T}{\partial z} dz.$$

Referring this temperature change to the spatial increment dm , we obtain

$$\frac{dT}{dm} = \frac{\partial T}{\partial x} \frac{dx}{dm} + \frac{\partial T}{\partial y} \frac{dy}{dm} + \frac{\partial T}{\partial z} \frac{dz}{dm}.$$

Now recall that $\frac{dx}{dm}$, $\frac{dy}{dm}$, $\frac{dz}{dm}$ are components of vector $\hat{\mathbf{m}}$. Introducing vector $\nabla T = \frac{\partial T}{\partial x}\hat{\mathbf{i}} + \frac{\partial T}{\partial y}\hat{\mathbf{j}} + \frac{\partial T}{\partial z}\hat{\mathbf{k}}$ and

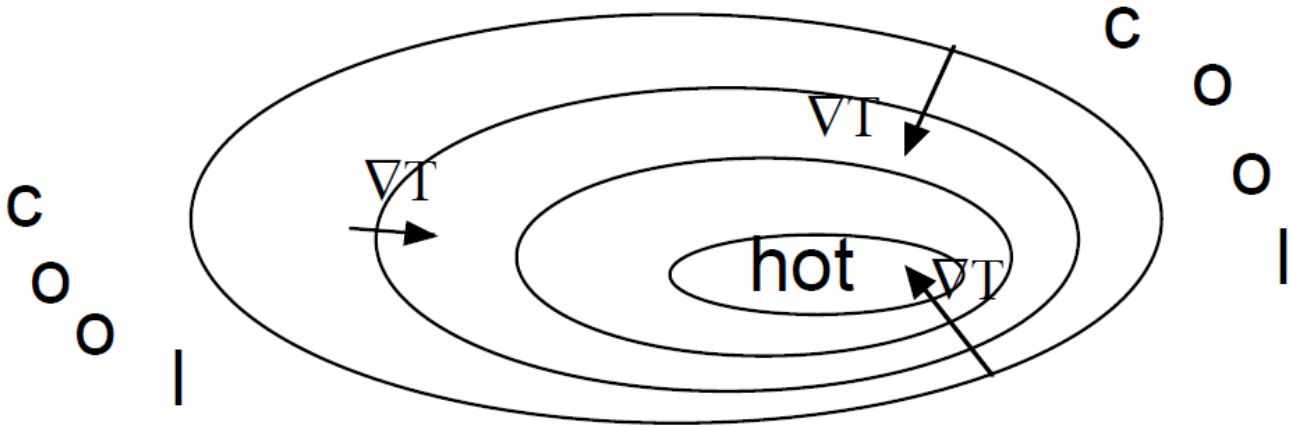
employing the dot product formalism, one may therefore write

$$\frac{dT}{dm} = \frac{\partial T}{\partial x} \frac{dx}{dm} + \frac{\partial T}{\partial y} \frac{dy}{dm} + \frac{\partial T}{\partial z} \frac{dz}{dm} = \left(\frac{\partial T}{\partial x}\hat{\mathbf{i}} + \frac{\partial T}{\partial y}\hat{\mathbf{j}} + \frac{\partial T}{\partial z}\hat{\mathbf{k}} \right) \cdot \left(\frac{dx}{dm}\hat{\mathbf{i}} + \frac{dy}{dm}\hat{\mathbf{j}} + \frac{dz}{dm}\hat{\mathbf{k}} \right) = \nabla T \cdot \hat{\mathbf{m}},$$

so the directional derivative (rate of change) of T in the direction of interest specified by unit vector $\hat{\mathbf{m}}$ is given by a scalar product of the vector ∇T , which is called the *gradient* of scalar field $T(x, y, z)$ (temperature), and the unit vector $\hat{\mathbf{m}}$:

$$\frac{dT}{dm} = \nabla T \cdot \hat{\mathbf{m}}.$$

It follows from the above expression that when the gradient vector is directed normal to $\hat{\mathbf{m}}$, the rate of change $\frac{dT}{dm} = 0$, so ∇T is directed perpendicular to the line (surface) of constant T (in this case it would be called isotherm). When $\hat{\mathbf{m}}$ is in direction of ∇T , the largest positive value of $\frac{dT}{dm}$ is attained, so ∇T points in the direction of greatest spatial change of T from lower to higher temperature values (see illustration below).



3. Del (nabla) operator

Operator ∇ , defined as

$$\nabla \equiv \frac{\partial}{\partial x} \hat{\mathbf{i}} + \frac{\partial}{\partial y} \hat{\mathbf{j}} + \frac{\partial}{\partial z} \hat{\mathbf{k}},$$

is called the *del* (or *nabla*) operator. It is considered a vector operator because in many respects it behaves like a vector.

In Cartesian coordinates, del operator ∇ acting on an arbitrary scalar field $F(x, y, z)$ produces a vector ∇F with components $\frac{\partial F}{\partial x}$, $\frac{\partial F}{\partial y}$, $\frac{\partial F}{\partial z}$ (as was shown in p. 2 using example of temperature), so

$$\nabla F = \frac{\partial F}{\partial x} \hat{\mathbf{i}} + \frac{\partial F}{\partial y} \hat{\mathbf{j}} + \frac{\partial F}{\partial z} \hat{\mathbf{k}}.$$

Action of the del operator ∇ on an arbitrary vector field $\mathbf{U}(x, y, z)$ has two forms.

Action in the form $\nabla \cdot \mathbf{U}$ (scalar/dot product of ∇ and \mathbf{U}) produces a scalar which is called the *divergence* of \mathbf{U} . Action in the form $\nabla \times \mathbf{U}$ (vector/cross product of ∇ and \mathbf{U}) produces a vector which is called the *curl* of \mathbf{U} .

Operation $\mathbf{U} \cdot \nabla$ (**note** that it is different to the divergence $\nabla \cdot \mathbf{U}$) results in a scalar operator, while further applying it to \mathbf{U} produces a vector $(\mathbf{U} \cdot \nabla)\mathbf{U}$. On the other hand, $(\nabla \cdot \mathbf{U})\mathbf{U} = \mathbf{U}(\nabla \cdot \mathbf{U})$ (a vector multiplied by a scalar) is also a vector, but not the same as $(\mathbf{U} \cdot \nabla)\mathbf{U}$. In this sense, operation $\mathbf{U} \cdot \nabla$ is not commutative.

Divergence

Take $\nabla \cdot$ (an arbitrary vector field \vec{a}):

$$\begin{aligned}\nabla \cdot \vec{a} &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right) \\ &= \hat{i} \frac{\partial}{\partial x} \cdot \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right) \\ &\quad + \hat{j} \frac{\partial}{\partial y} \cdot \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right) \\ &\quad + \hat{k} \frac{\partial}{\partial z} \cdot \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right)\end{aligned}$$

Expand out all the terms and recall that, $\hat{i} \cdot \hat{i} = 1$, $\hat{i} \cdot \hat{j} = 0$, $\hat{i} \cdot \hat{k} = 0$, etc. Get:

$$\nabla \cdot \vec{a} = \frac{\partial a_x}{\partial x} + \frac{\partial a_y}{\partial y} + \frac{\partial a_z}{\partial z}.$$

This is known as the divergence of \vec{a} . Note that \vec{a} is a vector and ∇ is a vector operator. But $\nabla \cdot \vec{a}$ is a scalar (much as the dot product between 2 vectors is a scalar).

Curl

Consider an arbitrary vector field \vec{a} . See what happens when you take $\nabla \times \vec{a}$:

$$\begin{aligned}\nabla \times \vec{a} &= \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \times \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right) \\ &= \hat{i} \frac{\partial}{\partial x} \times \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right) \\ &\quad + \hat{j} \frac{\partial}{\partial y} \times \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right) \\ &\quad + \hat{k} \frac{\partial}{\partial z} \times \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right)\end{aligned}$$

Expand out all the terms and recall that, $\hat{i} \times \hat{i} = 0$, $\hat{i} \times \hat{j} = \hat{k}$, $\hat{i} \times \hat{k} = -\hat{j}$, etc. Get:

$$\begin{aligned}\nabla \times \vec{a} &= \hat{i} \left(\frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \right) + \hat{j} \left(\frac{\partial a_x}{\partial z} - \frac{\partial a_z}{\partial x} \right) \\ &\quad + \hat{k} \left(\frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \right).\end{aligned}$$

$\nabla \times \vec{a}$ is known as the curl of \vec{a} . It is a vector!

Don't want to memorize that nasty formula for $\nabla \times \vec{a}$? No problem! The curl can also be written as a determinant:

$$\nabla \times \vec{a} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \times \left(\hat{i} a_x + \hat{j} a_y + \hat{k} a_z \right)$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ a_x & a_y & a_z \end{vmatrix}$$

$$= \hat{i} \left(\frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \right) + \hat{j} \left(\frac{\partial a_x}{\partial z} - \frac{\partial a_z}{\partial x} \right) + \hat{k} \left(\frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \right).$$

Same result as before.

Differentiation formulas involving ∇

If \vec{a} and \vec{b} are vectors and f is a scalar then,

$$\nabla \cdot (\vec{a} + \vec{b}) = \nabla \cdot \vec{a} + \nabla \cdot \vec{b},$$

$$\nabla \times (\vec{a} + \vec{b}) = \nabla \times \vec{a} + \nabla \times \vec{b},$$

$$\nabla \cdot (f\vec{a}) = f(\nabla \cdot \vec{a}) + (\nabla f) \cdot \vec{a},$$

$$\nabla \times (f\vec{a}) = f(\nabla \times \vec{a}) + (\nabla f) \times \vec{a},$$

$$\nabla \cdot (\vec{a} \times \vec{b}) = \vec{b} \cdot (\nabla \times \vec{a}) - \vec{a} \cdot (\nabla \times \vec{b}),$$

$$\begin{aligned} \nabla \times (\vec{a} \times \vec{b}) &= \vec{a}(\nabla \cdot \vec{b}) + (\vec{b} \cdot \nabla) \vec{a} \\ &\quad - \vec{b}(\nabla \cdot \vec{a}) - (\vec{a} \cdot \nabla) \vec{b}, \end{aligned}$$

$$\begin{aligned} \nabla (\vec{a} \cdot \vec{b}) &= (\vec{a} \cdot \nabla) \vec{b} + (\vec{b} \cdot \nabla) \vec{a} \\ &\quad + \vec{a} \times (\nabla \times \vec{b}) + \vec{b} \times (\nabla \times \vec{a}). \end{aligned}$$